



# GEOSTROPHIC WINDS WITH A FULL REPRESENTATION OF THE CORIOLIS FORCE: APPLICATION TO IR OBSERVATIONS OF THE UPPER JOVIAN TROPOSPHERE.

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- Introduction.
- The full 3D and the primitive equations.
- Geostrophic balance in both approaches.
- Thermal winds.
- Comparing the approaches.
- Summary.



## Introduction

### MOTIVATION:

- **Scientific:** Assessing the validity of the geostrophic origin of planetary winds.
- **Technical:** Remote sensing of velocity in planetary atmospheres.
  - i) Tracking of visible features.
  - ii) Geostrophic diagnostics using temperature maps.

### OBJECTIVES:

1. To formulate geostrophic balance with a full Coriolis force in a stratified atmosphere.
2. To compare with the diagnostics from the primitive equations.

DATA: Infrared maps of Jovian temperatures. 4 different pressure levels.

## Inviscid full and primitive equations:

<b>Full 3D:</b>	$\left( \frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \vec{\nabla} \vec{v} + CT \right) + 2\Omega \vec{k} \wedge \vec{v} = -\frac{\vec{\nabla} p}{\rho} + \vec{F}$
<b>Primitive:</b>	$\left( \frac{\partial \vec{v}_h}{\partial t} + \vec{v} \cdot \vec{\nabla} \vec{v}_h + PECT \right) + f \vec{e}_r \wedge \vec{v}_h = -\frac{\vec{\nabla} p}{\rho} + \vec{F} + O(w)$

$r$  = Radial coordinate ;  $\lambda$  = Latitude ;  $\varphi$  = Longitude ;

$\vec{k} = \vec{e}_r \sin \lambda + \vec{e}_\lambda \cos \lambda$  ;  $f = 2\Omega \sin \lambda$  ;  $z = r - R_{planet}$ ;

$\vec{v} = (u, v, w)$  ;  $\vec{v}_h = (u, v, 0)$

$\frac{\partial}{\partial x} = \frac{1}{r \cos \lambda} \frac{\partial}{\partial \varphi}$  ;  $\frac{\partial}{\partial y} = \frac{1}{r} \frac{\partial}{\partial \lambda}$

$CT$ : Curvature terms ;  $PECT$ : Curvature terms in the Primitive equations;



[DN.004] Geostrophic winds with a full representation  
of the Coriolis force. (DFD-53)

INVISCID FULL AND PRIMITIVE EQUATIONS:

<b>Full 3D:</b> $\left( \frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \vec{\nabla} \vec{v} + CT \right) + 2\Omega \vec{k} \wedge \vec{v} = -\frac{\vec{\nabla} p}{\rho} + \vec{F}$
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$$\frac{\partial u}{\partial t} + \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) u - \left( 2\Omega + \frac{u}{r \cos \lambda} \right) (v \sin \lambda - w \cos \lambda) + DSCT = -\frac{1}{\rho} \frac{\partial p}{\partial x} + F_x$$

$$\frac{\partial v}{\partial t} + \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v + \left( 2\Omega + \frac{u}{r \cos \lambda} \right) u \sin \lambda + \frac{wv}{r} + DSCT = -\frac{1}{\rho} \frac{\partial p}{\partial y} + F_y$$

$$\frac{\partial w}{\partial t} + \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) w - \left( 2\Omega + \frac{u}{r \cos \lambda} \right) u \cos \lambda - \frac{v^2}{r} + DSCT = -\frac{1}{\rho} \frac{\partial p}{\partial z} - g + F_z$$

$$\frac{D\rho}{Dt} + \rho \vec{\nabla} \cdot \vec{v} = \frac{D\rho}{Dt} + \rho \left( \frac{\partial u}{\partial x} + \frac{\partial(v \cos \lambda)}{\partial y} + \frac{1}{r^2} \frac{\partial(r^2 w)}{\partial z} \right)$$

<b>Primitive:</b> $\left( \frac{\partial \vec{v}_h}{\partial t} + \vec{v} \cdot \vec{\nabla} \vec{v}_h + PECT \right) + f \vec{e}_r \wedge \vec{v}_h = -\frac{\vec{\nabla} p}{\rho} + \vec{F} + O(w)$
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$$\frac{\partial u}{\partial t} + \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) u - \left( 2\Omega + \frac{u}{r \cos \lambda} \right) (v \sin \lambda) = -\frac{1}{\rho} \frac{\partial p}{\partial x} + F_x + O(w)$$

$$\frac{\partial v}{\partial t} + \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v + \left( 2\Omega + \frac{u}{r \cos \lambda} \right) u \sin \lambda = -\frac{1}{\rho} \frac{\partial p}{\partial y} + F_y + O(w)$$

$$0 = -\frac{1}{\rho} \frac{\partial p}{\partial z} - g + O(w, F_z)$$

$$\frac{D\rho}{Dt} + \rho \vec{\nabla} \cdot \vec{v} = \frac{D\rho}{Dt} + \rho \left( \frac{\partial u}{\partial x} + \frac{\partial(v \cos \lambda)}{\partial y} + \frac{\partial w}{\partial z} \right)$$

$r$  = Radial coordinate ;  $\lambda$  = Latitude ;  $\varphi$  = Longitude ;

$\vec{k} = \vec{e}_r \sin \lambda + \vec{e}_\lambda \cos \lambda$  ;  $f = 2\Omega \sin \lambda$  ;  $z = r - R_{planet}$ ;

$\vec{v} = (u, v, w)$  ;  $\vec{v}_h = (u, v, 0)$

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$CT$ : Curvature terms ;  $PECT$ : Curvature terms in the Primitive equations;

$DSCT$ : Curvature terms - Curvature terms in shallow atmospheres;



## 0-th order solution - Hydrostatic balance:

For an ideal gas in hydrostatic balance:  $\vec{\nabla}p_h(z) = \rho_h(z)\vec{g}$ ;  $\vec{v} = 0$ .

## 1-st order solution - Geostrophic balance:

$\vec{v} \sim \epsilon\vec{v}_g \sim \epsilon\vec{v}_{gp}$  (velocity in geostrophic balance).

$Ro \sim (\vec{\nabla} \wedge \vec{v})/2\Omega$  (Rossby number).

Introducing:  $\vec{\nabla}\pi = \vec{\nabla}p_h(z) + \epsilon\vec{\nabla}\pi_1(x, y, z)$

$\vec{\nabla}\pi \equiv \vec{\nabla}p + \rho\vec{\nabla}(v^2/2)$  (dynamic pressure)

Full 3D $O(Ro)$	
$2\Omega\vec{k} \wedge \vec{v}_g = \frac{1}{\epsilon} \left( -\frac{1}{\rho}\vec{\nabla}\pi + \vec{g} \right)$	$\vec{v}_g = \frac{\vec{k}}{\rho\epsilon 2\Omega} \wedge (\vec{\nabla}\pi - \rho\vec{g}) + V_g^0 \vec{k}$

Primitive $O(w, Ro)$	
$f\vec{e}_r \wedge \vec{v}_{gp} = \frac{1}{\epsilon} \left( -\frac{1}{\rho}\vec{\nabla}\pi + \vec{g} \right)$	$\vec{v}_{gp} = \frac{\vec{e}_r}{\rho\epsilon f} \wedge (\vec{\nabla}\pi - \rho\vec{g}) + V_{gp}^0 \vec{e}_r$

Geostrophic balance requires:

$$-\vec{k} \cdot (\vec{\nabla}\pi - \rho\vec{g}) = 0 \rightarrow \frac{1}{\rho} \frac{\partial\pi}{\partial Z} = \frac{1}{\rho} \left( \sin \lambda \frac{\partial\pi}{\partial z} + \cos \lambda \frac{\partial\pi}{\partial y} \right) = -g \sin \lambda$$

$$-\vec{e}_r \cdot (\vec{\nabla}\pi - \rho\vec{g}) = 0 \rightarrow \frac{1}{\rho} \frac{\partial\pi}{\partial z} = -g \quad (\text{hydrostatic approximation})$$

Note that:  $\vec{v}_g \perp \vec{k}$ , while  $\vec{v}_{gp} \perp \vec{e}_r$  (contained in the horizontal plane)

Full 3D (non-singular at $\lambda = 0$ )	Primitive (singular)
$\vec{v}_g = \frac{1}{\rho 2\Omega} \begin{pmatrix} -\sin \lambda \frac{\partial\pi_1}{\partial y} + \cos \lambda \left( \rho_1 g + \frac{\partial\pi_1}{\partial z} \right) \\ \sin \lambda \frac{\partial\pi_1}{\partial x} \\ -\cos \lambda \frac{\partial\pi_1}{\partial x} \end{pmatrix}$	$\vec{v}_{gp} = \frac{1}{\rho 2\Omega \sin \lambda} \begin{pmatrix} -\frac{\partial\pi_1}{\partial y} \\ \frac{\partial\pi_1}{\partial x} \\ 0 \end{pmatrix}$



## Thermal winds:

Taking the curl of the geostrophic balance condition and assuming static compressibility (anelastic approximation):  $\epsilon(2\vec{\Omega} \cdot \vec{\nabla})(\rho\vec{v}_g) = -\vec{\nabla}\rho \wedge \vec{g}$ .

$$\epsilon(f\vec{e}_r \cdot \vec{\nabla})(\rho\vec{v}_g) = -\vec{\nabla}\rho \wedge \vec{g}.$$

If  $Z^* \equiv Z/H$ , and  $z^* \equiv z/H$ , where  $1/H = -\partial(\ln p_h)/\partial z$ , leads to:

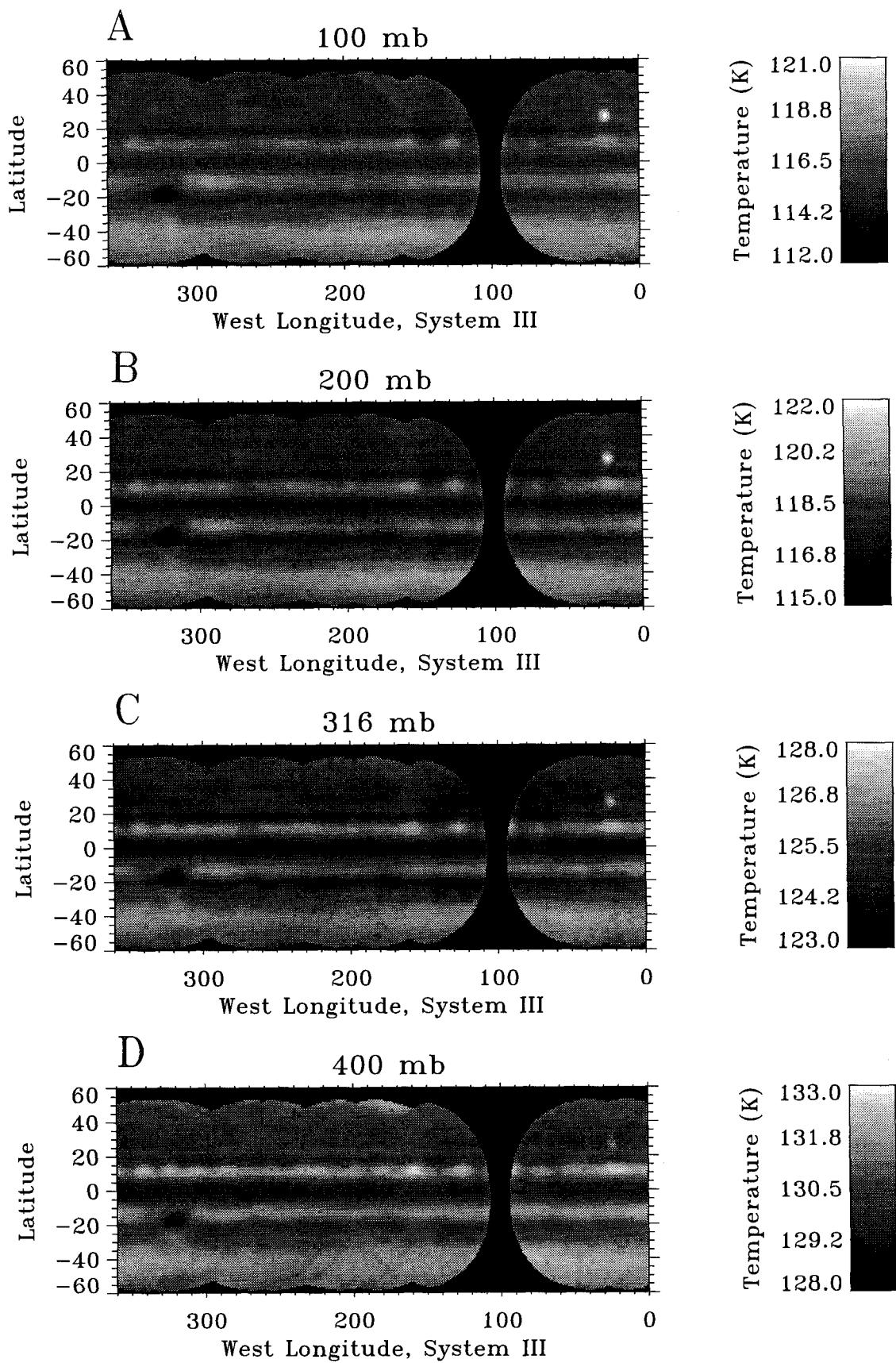
Full 3D $O(Ro, \epsilon)$	
$\frac{1}{\rho} \frac{\partial \rho u_g}{\partial Z^*} \equiv \frac{\partial u_g}{\partial Z_p^*}$	$= -\frac{R}{2\Omega M_r} \left( \frac{\partial T}{\partial y} \right)_{p_h}$
$\frac{1}{\rho} \frac{\partial \rho v_g}{\partial Z^*} \equiv \frac{\partial v_g}{\partial Z_p^*}$	$= \frac{R}{2\Omega M_r} \left( \frac{\partial T}{\partial x} \right)_{p_h}$
$\frac{1}{\rho} \frac{\partial \rho w_g}{\partial Z^*} \equiv \frac{\partial w_g}{\partial Z_p^*}$	$= O(\epsilon)$

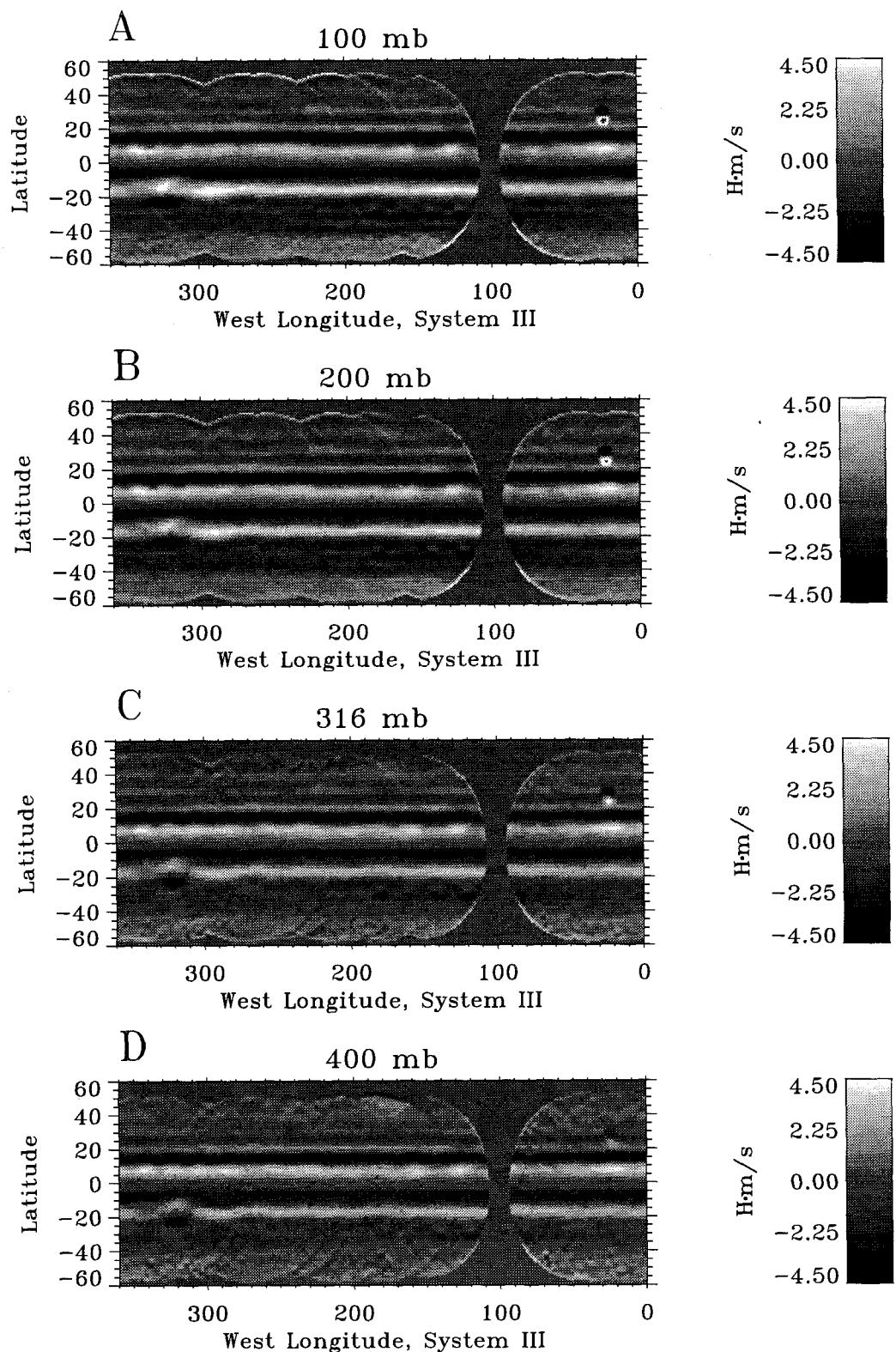
Primitive $O(w, Ro, \epsilon)$	
$\frac{\partial u_{gp}}{\partial z^*} = -\frac{R}{fM_r} \left( \frac{\partial T}{\partial y} \right)_p$	$\leftarrow$ The hydrostatic approximation has been used.
$\frac{\partial v_{gp}}{\partial z^*} = \frac{R}{fM_r} \left( \frac{\partial T}{\partial x} \right)_p$	

## Comparisons:

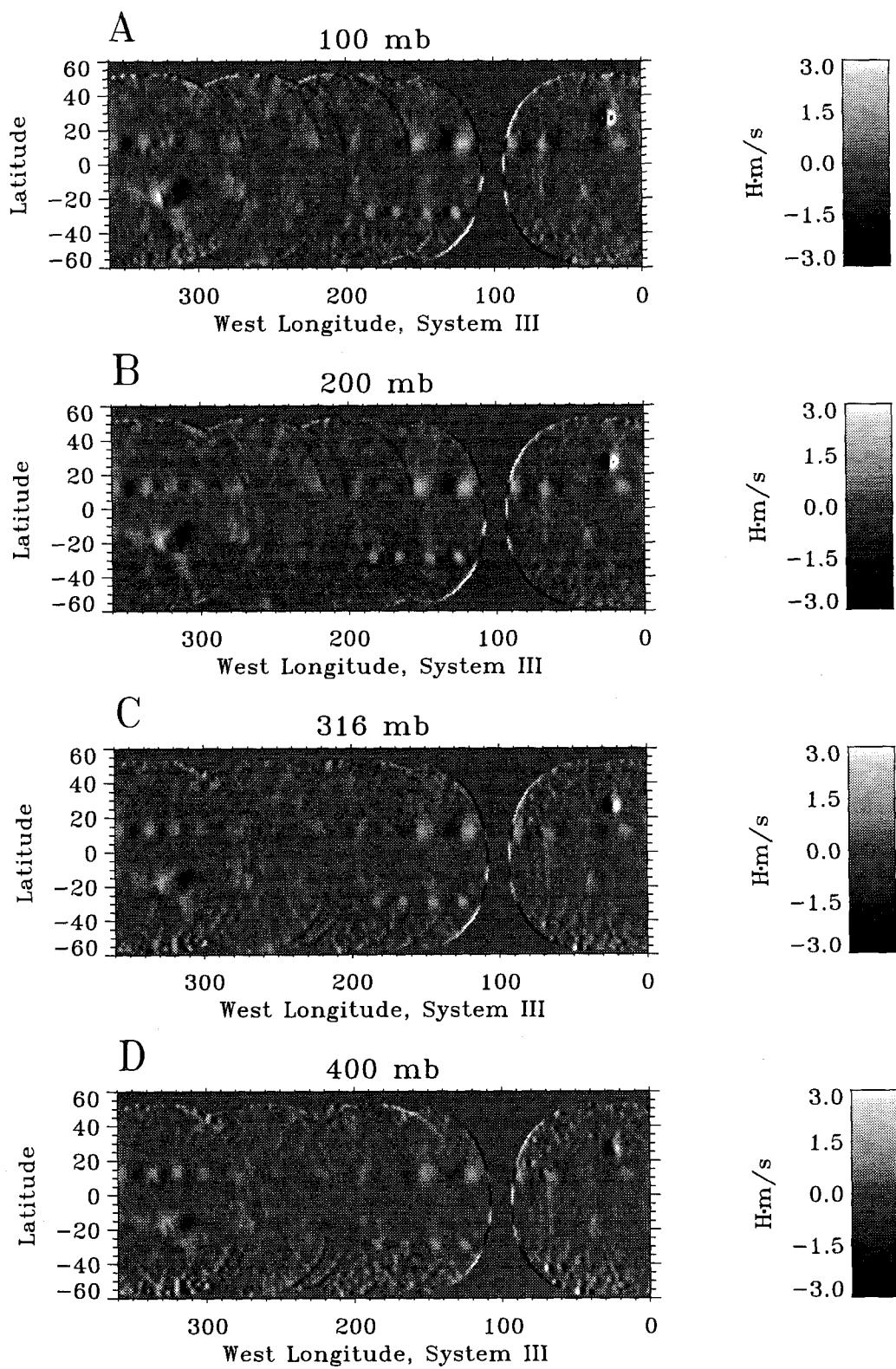
Non-hydrostatic $O(\epsilon)$	Hydrostatic $O(1)$
$\begin{cases} \frac{\partial u_g}{\partial z^*} = \frac{\partial u_{gp}}{\partial z^*} - H \cot \lambda \frac{\partial u_g}{\partial y} \\ \frac{\partial v_g}{\partial z^*} = \frac{\partial v_{gp}}{\partial z^*} - H \cot \lambda \frac{\partial v_g}{\partial y} \\ \frac{\partial \rho w_g}{\partial z^*} = -H \cot \lambda \frac{\partial \rho w_g}{\partial y} + O(\epsilon) \end{cases}$	$\begin{cases} \frac{\partial u_g}{\partial z^*} = -\frac{R \sin \lambda}{2\Omega M_r} \left( \frac{\partial T}{\partial y} \right)_p \\ \frac{\partial v_g}{\partial z^*} = \frac{R \sin \lambda}{2\Omega M_r} \left( \frac{\partial T}{\partial x} \right)_p \\ \frac{\partial w_g}{\partial z^*} = -\frac{R \cos \lambda}{2\Omega M_r} \left( \frac{\partial T}{\partial x} \right)_p \end{cases}$



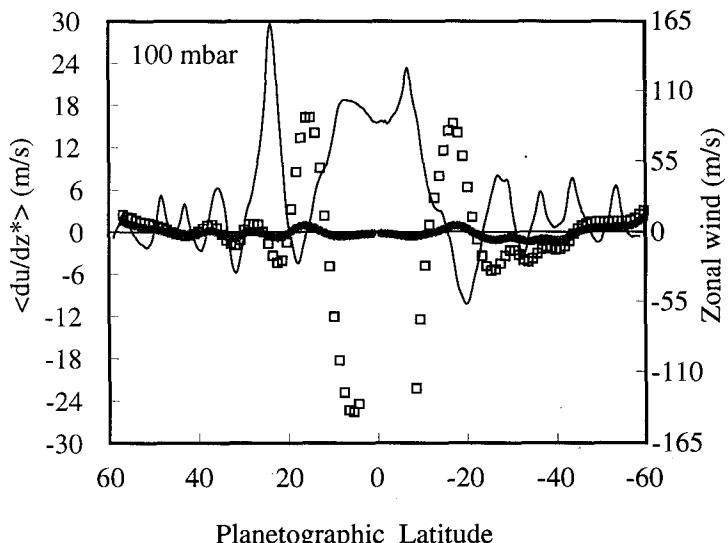
Figures 1 a-d



**Figures 2a-d**

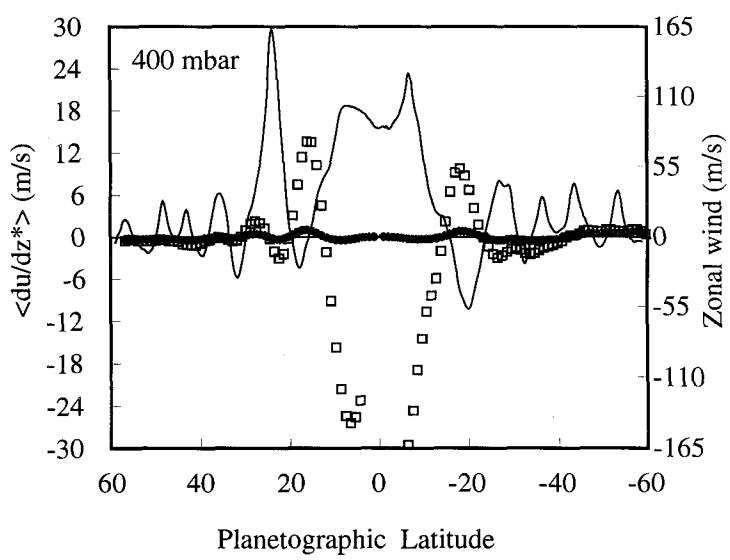


### Figures 3a-d



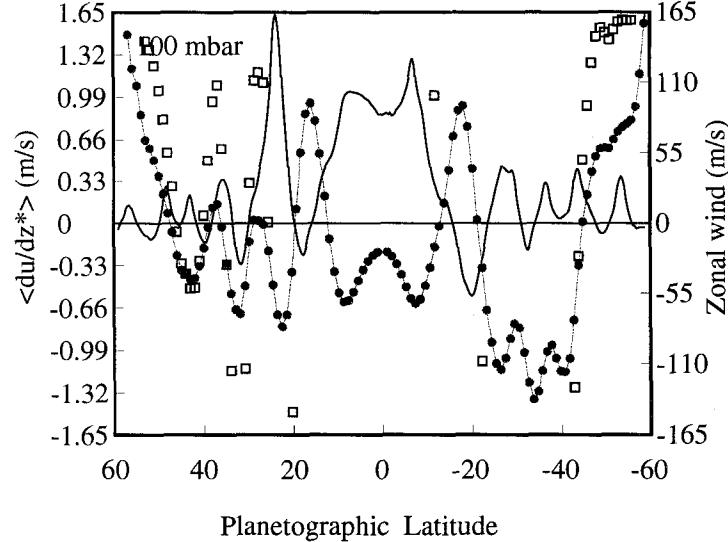
Planetographic Latitude

**Figure 4a**



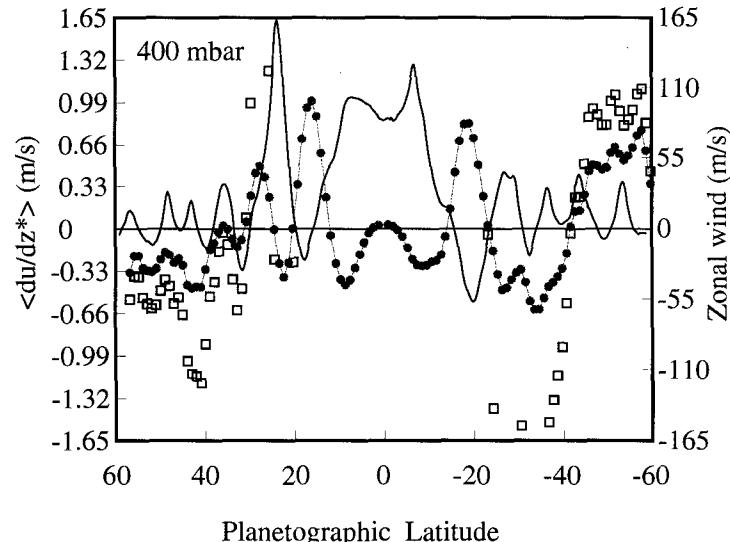
Planetographic Latitude

**Figure 4b**



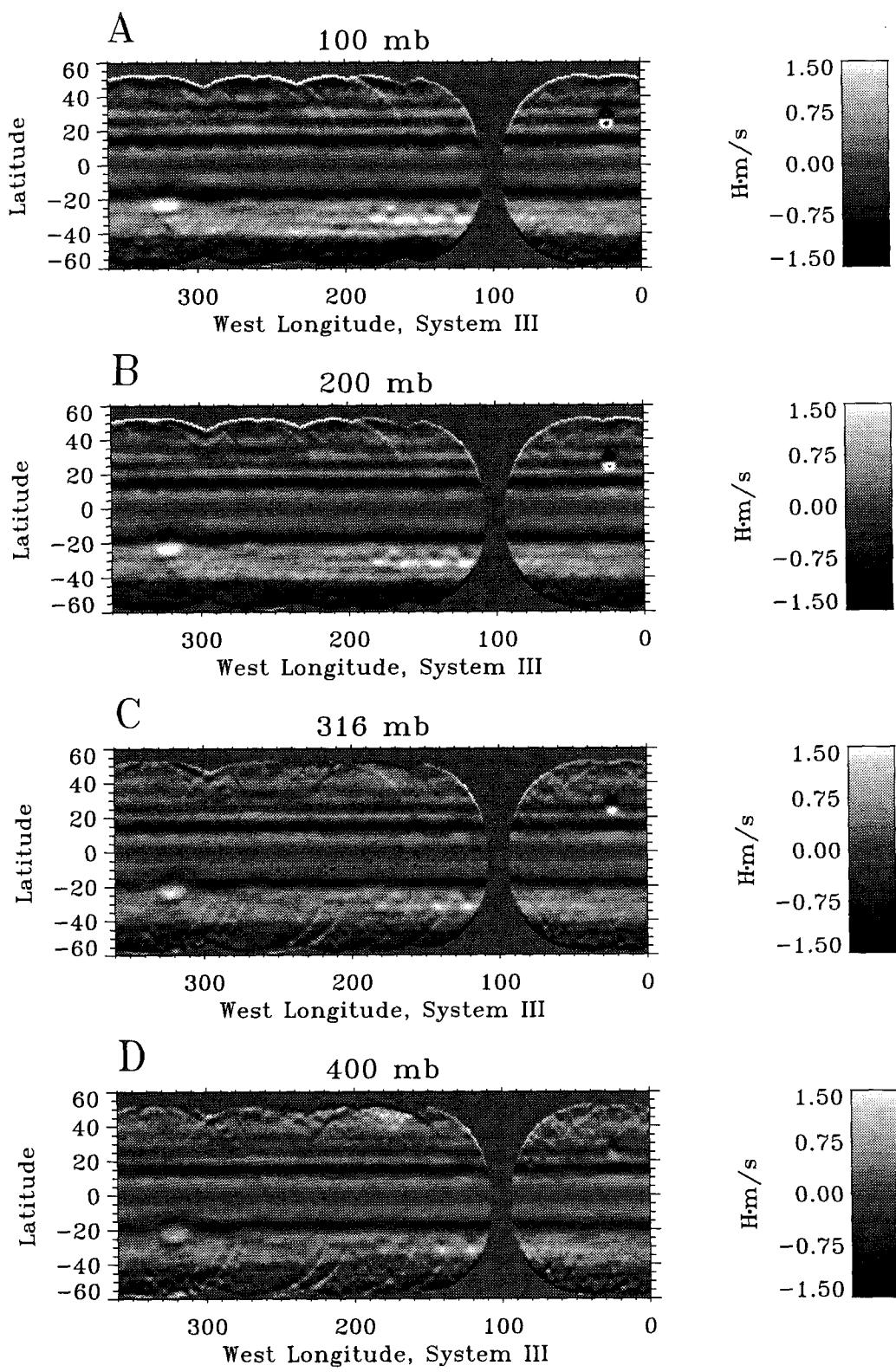
Planetographic Latitude

**Figure 4c**

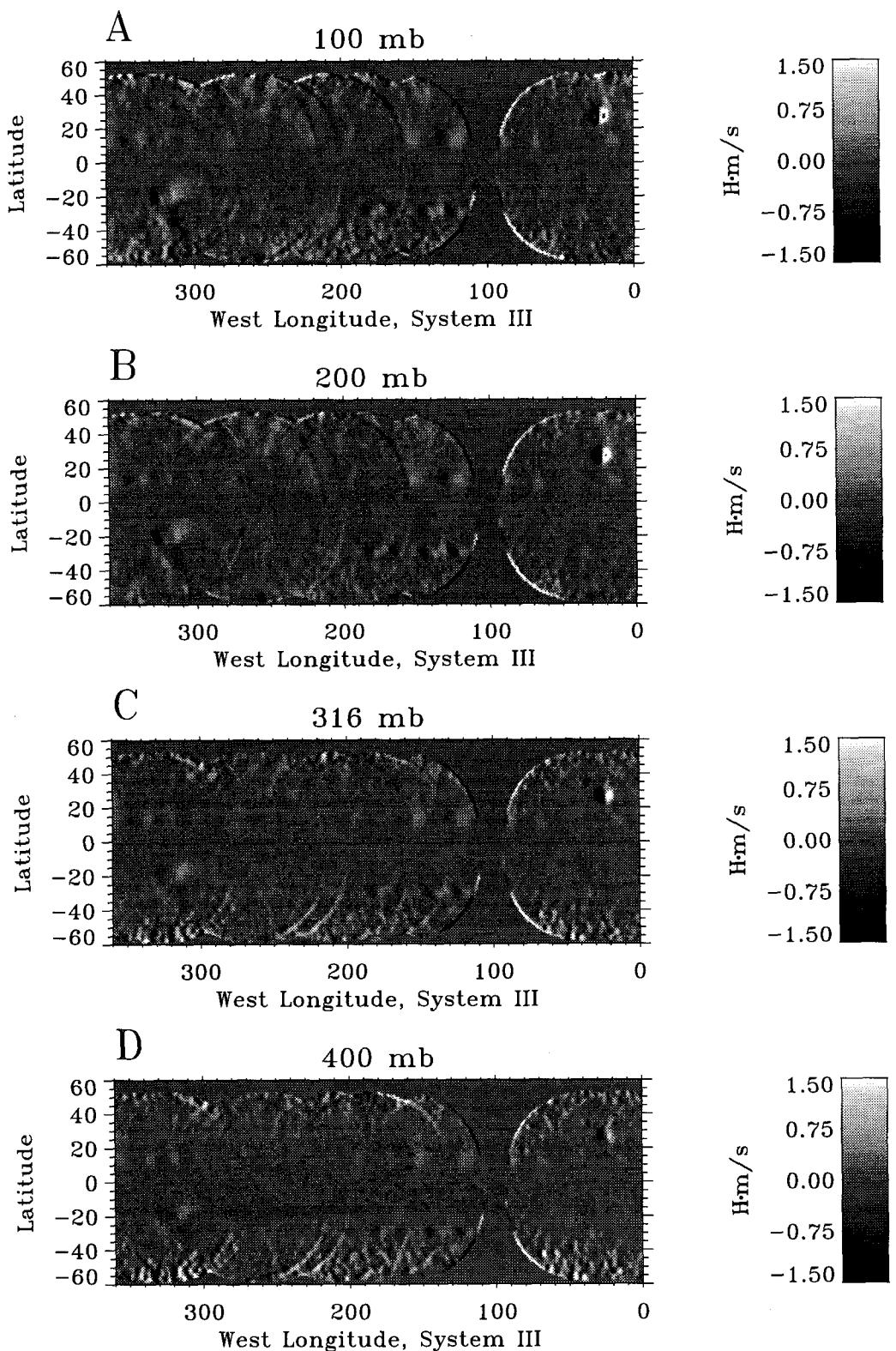


Planetographic Latitude

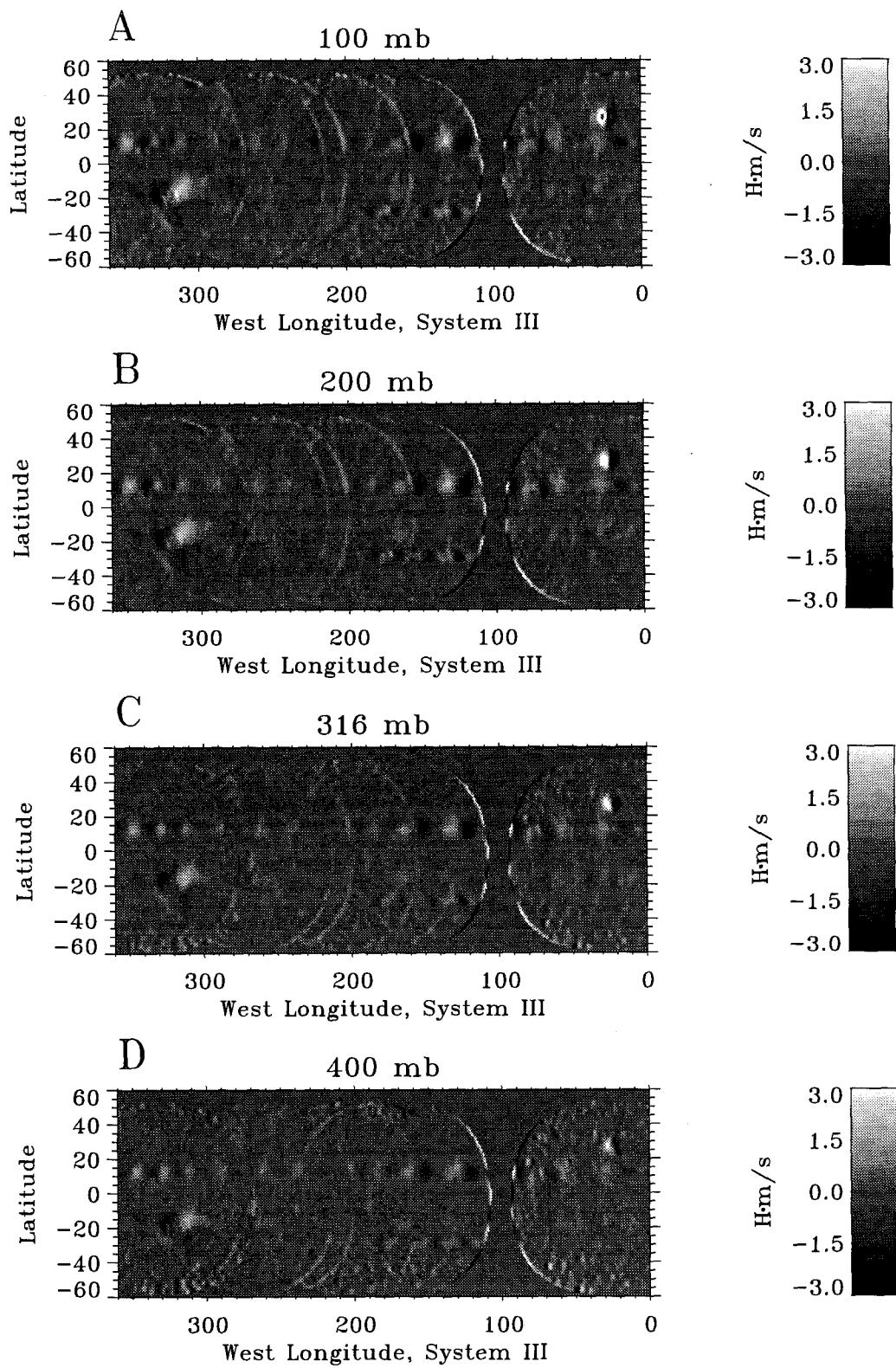
**Figure 4d**



**Figures 5a-d**



**Figures 6a-d**



**Figures 7a-d**